



Slovak real-time positioning service as an integral part of *EUPOS*

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Important Milestones for **SKPOS**



- Initial ideas about **SKPOS**
 - November 2001, Vienna - 2nd UN/USA Regional Workshop on the Use of GNSS
 - March 2002, Berlin – Workshop on Multifunctional Reference Stations Systems in Europe
- **SKPOS** realisation
 - Beginning of 2006 – **SKPOS** hardware purchase
 - May 2006 – first **SKPOS** station initialization (SKGA)
 - November 2006 – first official user registration
 - May 2007 – full **SKPOS** network constellation (21 stations)



Formation of *EUPOS*

- *EUPOS* is an international initiative and cooperation
- unified regional DGNSS ground-based infrastructure for real-time positioning and navigation
- mosaic of national segments operating according to common standards
- interoperability of the national positioning services



Slovak Real-Time Positioning Service - *SKPOS*



Legislation

- 2003 - amendment of the law on geodesy and cartography
- new task - to operate a GNSS real-time positioning service

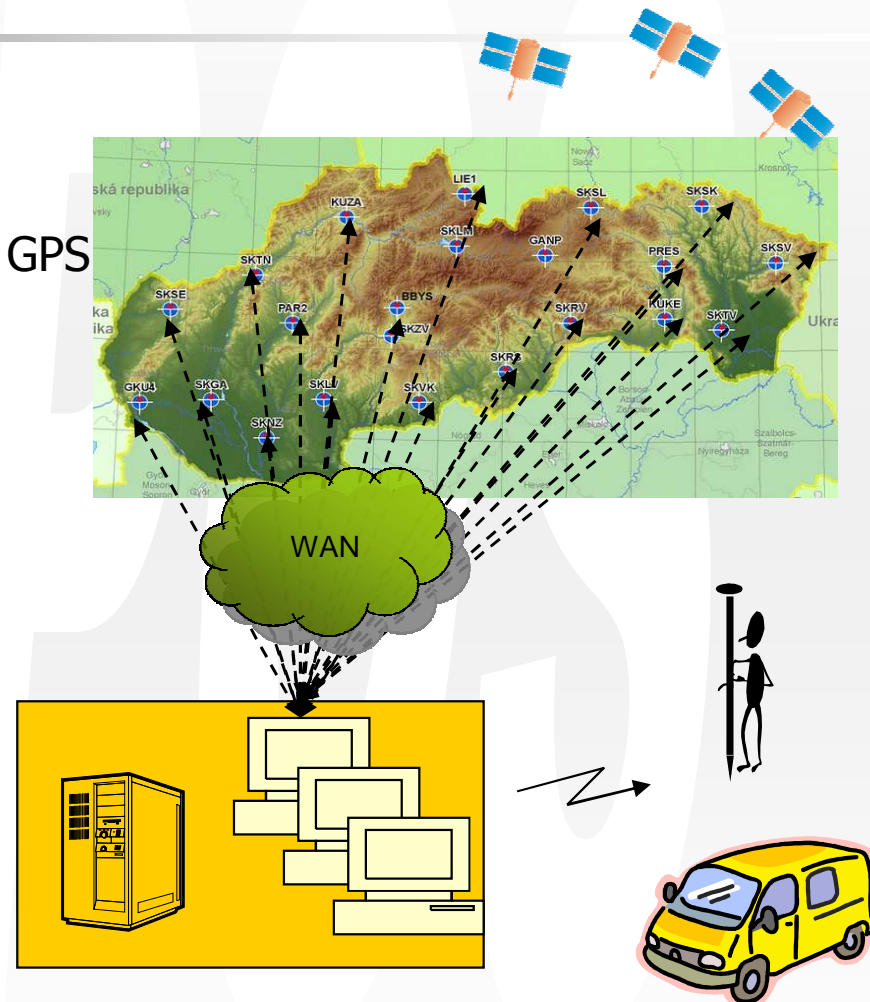


Financing

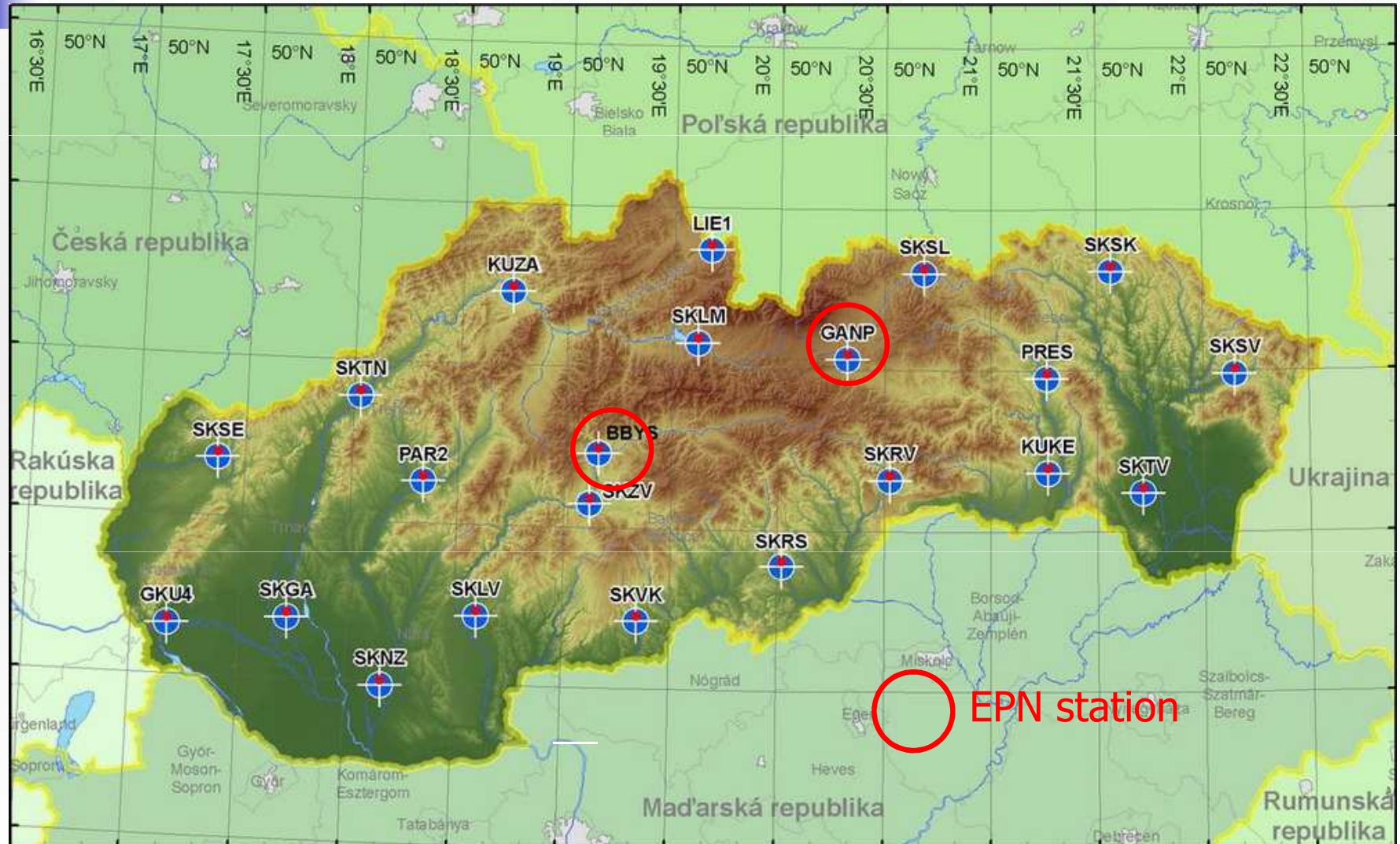
- pre-accession EU programme Phare
- financial memorandum 2003
- tender failed in 2005
- in 2006 - financing from the state budget
- since November 2006 - **SKPOS** in operation

SKPOS Infrastructure

- reference stations network
 - 21 stations (GPS/GLONASS) + 1 external GPS station
 - receivers: Trimble NETR5
 - antennas: Zephyr Geodetic Model 2
- communication lines
 - virtual private network
 - GNSS data have highest priority
 - cadastral data
- National Service Centre
 - Trimble networking software
 - Bernese GPS software 5.0



Distribution of the reference stations



Monumentations



Antenna calibration on robot



← BERLIN -Senatstadt

GARBSEN – Geo++ →



A graphic element consisting of a vertical black line, a horizontal black line, and two overlapping squares (one red, one blue) positioned to the left of the main title.

SKPOS services

real-time services

- **SKPOS-dm** — differential corrections by code measurements, accuracy **1 m – 0,5 m for dynamic objects and 0,3 m for static objects**
- **SKPOS-cm** — differential corrections by carrier phase measurements, accuracy **2 – 4 cm.**

post-processing services

- **SKPOS-mm** — code and phase measurements for postprocessing, centimetre to sub – centimetre accuracy

Data distribution

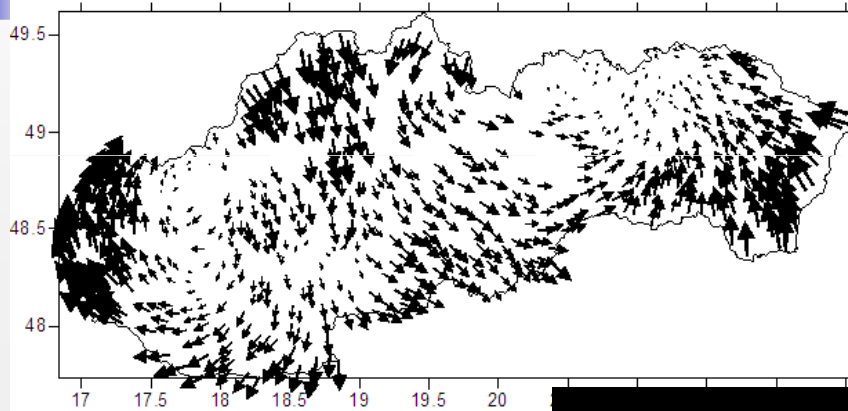
SKPOS-dm	NTRIP caster	http://www.skpos.gku.sk:2101/	free of charge
SKPOS-cm	NTRIP caster	http://www.skpos.gku.sk:2101/	free of charge
SKPOS-mm	web server	http://www.skpos.gku.sk	charged



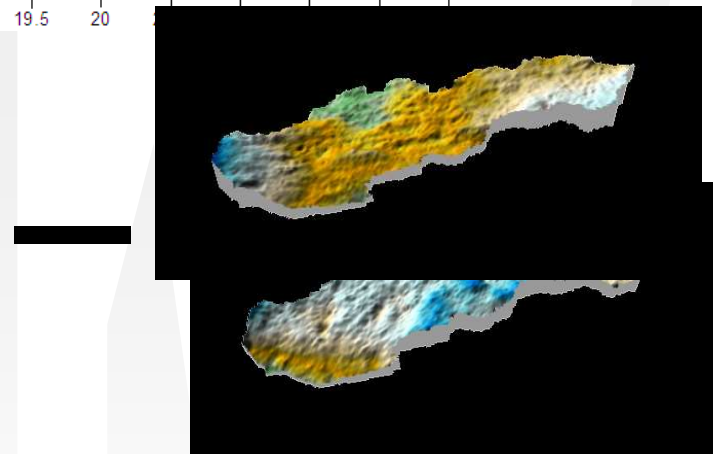
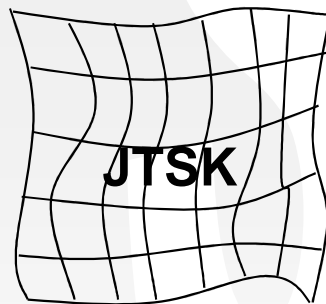
Close Cross-border cooperation

- Main activity
 - Providing data (RTCM, Rinex) for other neighboring services
 - GNSSnet.hu, ASG-EUPOS, APOS, CZEPOS
 - Comparison of processing results - coordinates and time series character on overlap stations.
- Purpose
 - Verification of processing strategy,
 - Verification of station quality,
 - Improved RTK surveying accuracy in close border areas.
- Example of results
 - Comparison consistency on cm level with AGS-EUPOS, APOS, GNSSnet.hu,
 - Recognized false antenna calibration on WIEN station.

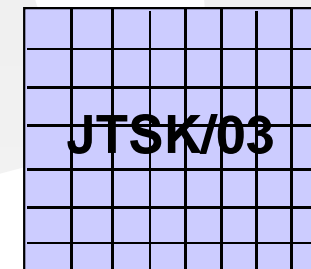
Transformation into the national coordinate system



local distortions up to 1.3 m



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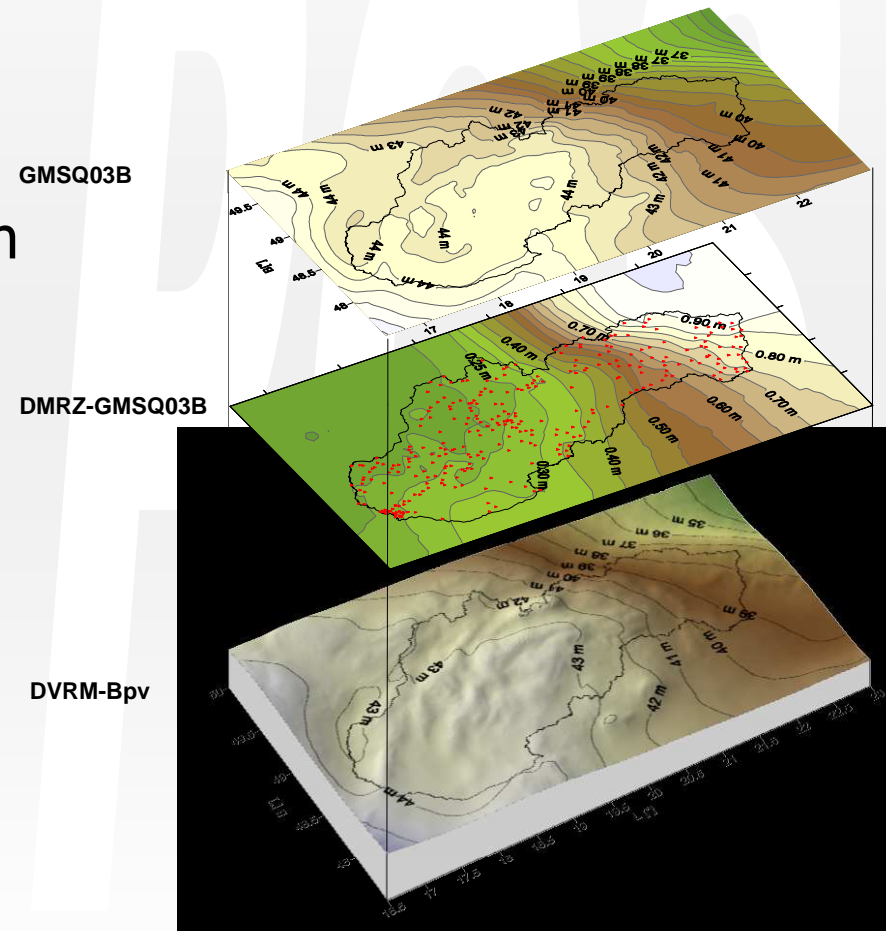
ETRS89



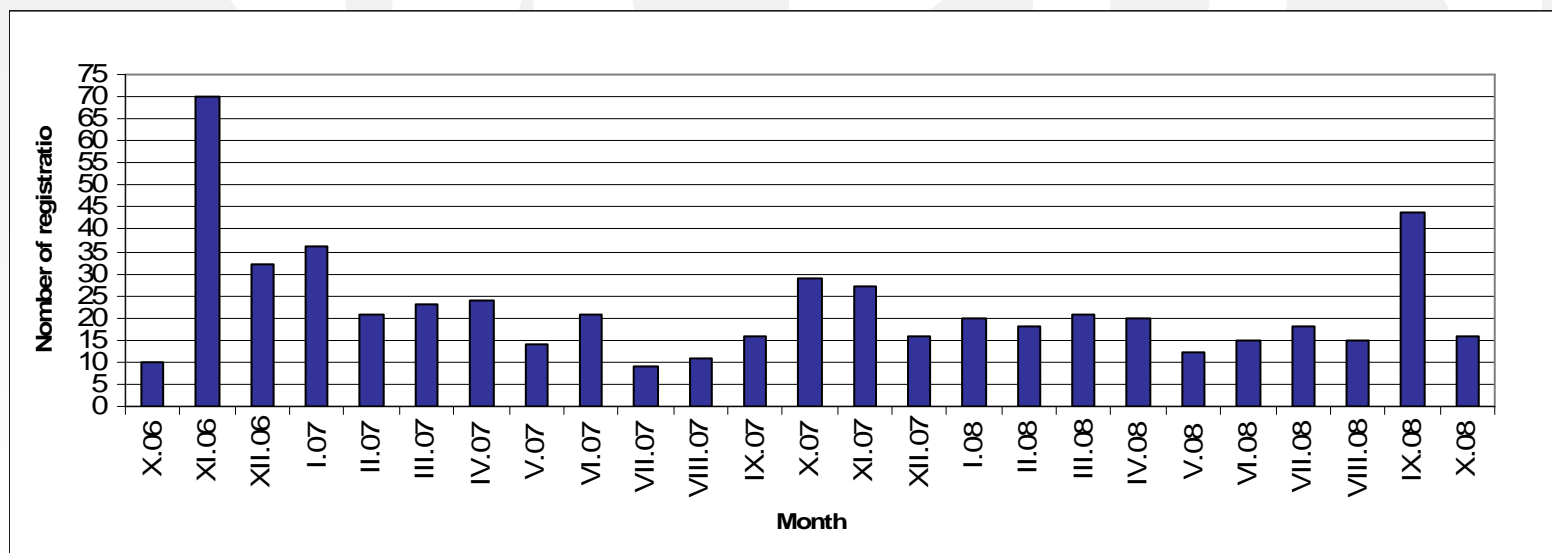
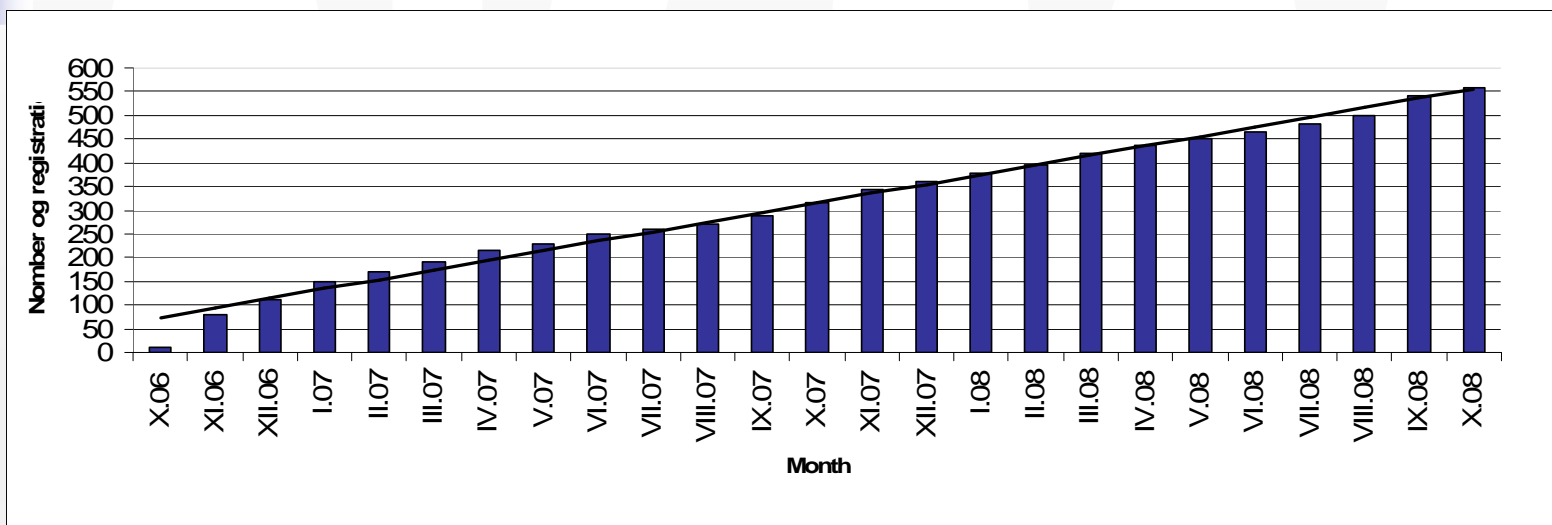
Global par.
tX = 485.021 m
tY = 169.465 m
tZ = 483.839 m
uX = -7.786342
uY = -4.397554
uZ = -4.102655
dK = 0

Transformation into the national height system

- gridded data 600 x 600 m
- accuracy of the transformation 3.5 cm (1σ)



SKPOS users





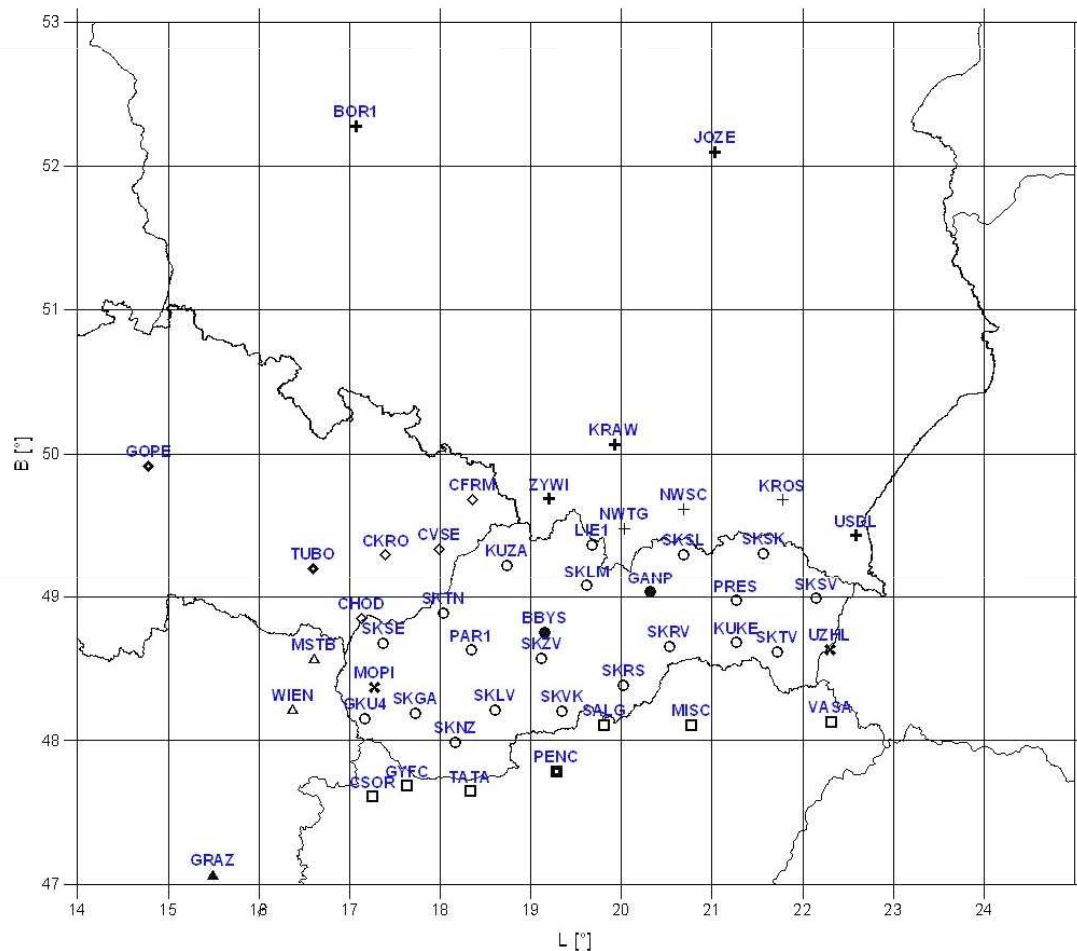
SKPOS coordinates

- Bernese GPS software v.5.0
- Fixed to EPN/IGS stations
- ITRF2000
- ETRF2000 (epoch 2006.636)

Monitoring of the network stations stability

- Routine processing of 49 stations
 - Bernese Software 5.0,
 - ITRF2005 (epoch 2000.0),
 - GLONASS included,
 - Results = sets of daily and weekly coordinates and covariances
- Residuals creation
 - Modified strategy developed by LAC SUT,
 - Transformation to „*neu*“ topocentric system,
 - Graphic interpretation (weekly residuals) as time series
- Time series analysis
 - Least square estimation of the 1st order of harmonic analysis,
 - Trend and annual period determination.
- Conclusions and results
 - Comparison with critic values,
 - Stations sorting according results (stable, periodic, outlier...),
 - Solving detected and unexpected station character

Processed stations network



<i>SKPOS</i>	23/3 EPN
<i>APOS</i>	3/1 EPN
<i>GNSSnet.hu</i>	7/1 EPN
<i>CZEPOS</i>	6/2 EPN
<i>ASG-EUPOS</i>	8/5 EPN
EPN	2
Totally	49 stations



Residuals creation

- Residual equation
 - Reduction of mean network (LAC SUT strategy),
 - BOR1 – reference point,
 - ITRF2005 velocity model

$$d\mathbf{X}_i(t) = \mathbf{X}_i(t) - \mathbf{X}_{O_i} - \mathbf{v}_{ITRF\ 2005_i}(t - t_o) - \mathbf{A} \cdot \mathbf{T}$$

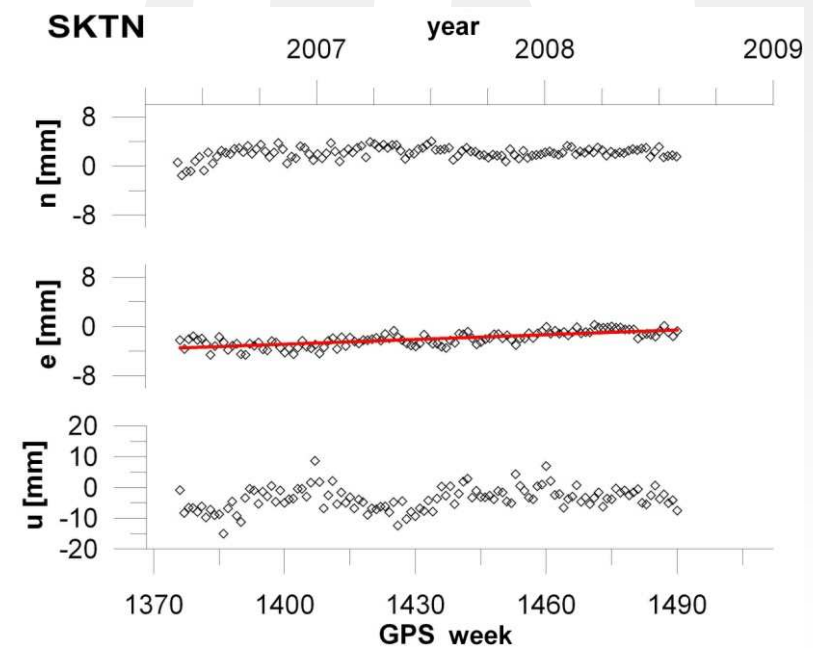
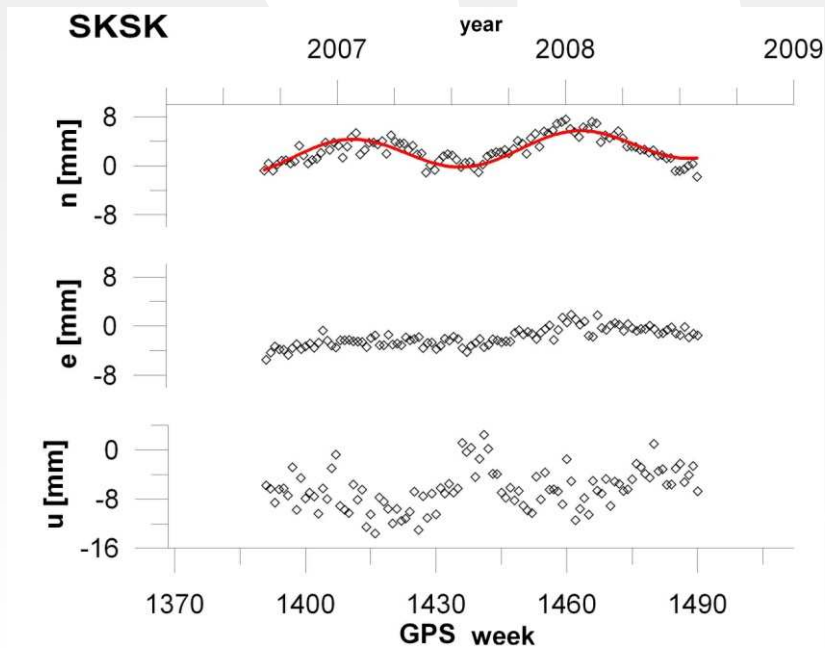
- Topocentric system

$$d\mathbf{N}_i(t) = \begin{pmatrix} dn_i(t) \\ de_i(t) \\ du_i(t) \end{pmatrix} = \mathbf{R}(B_i, L_i) \cdot d\mathbf{X}_i(t)$$

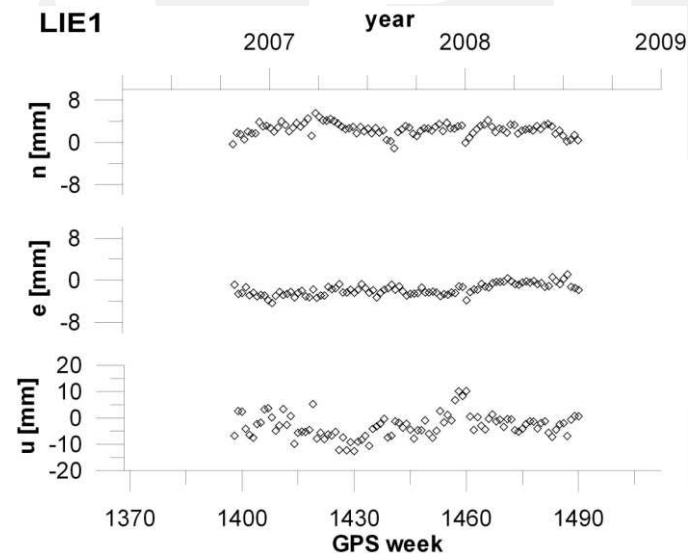
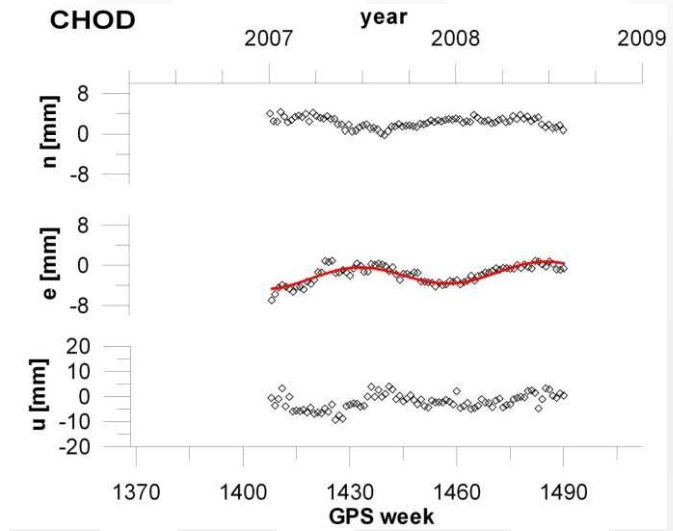
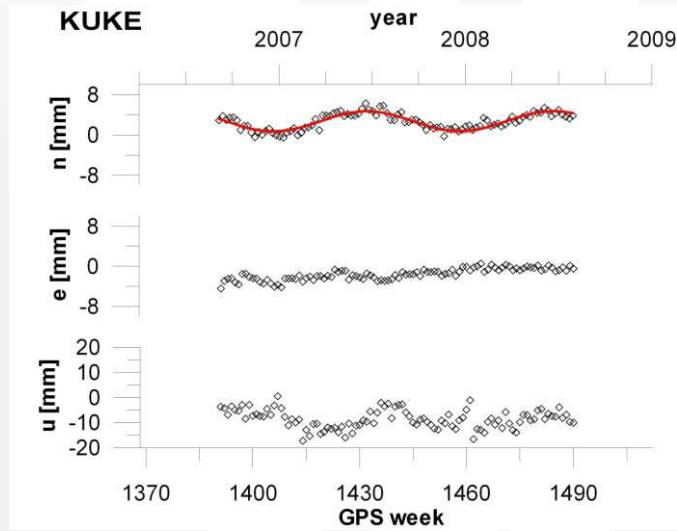
Timeseries analysis

- 1st order harmonic analysis (a - trend, Λ - periodicity).

$$y = \mathbf{a} \cdot t + b + \Lambda \cdot \cos\left(\frac{2 \cdot \pi}{52} \cdot t - \varphi\right)$$



Time series other examples





Future plans for development

- Hardware
 - densification of the network: 3 – 4 more GNSS stations,
 - independent quality monitoring stations,
 - absolute phase centre calibration of all antennas
- Software, computation and analysis
 - Continual transition to ETRF2005 in net software,
 - Contribute to evaluation of systematic effects (multipath) and troposphere modeling,
 - Enhanced quality of transformation to national 2D system and local vertical datum.